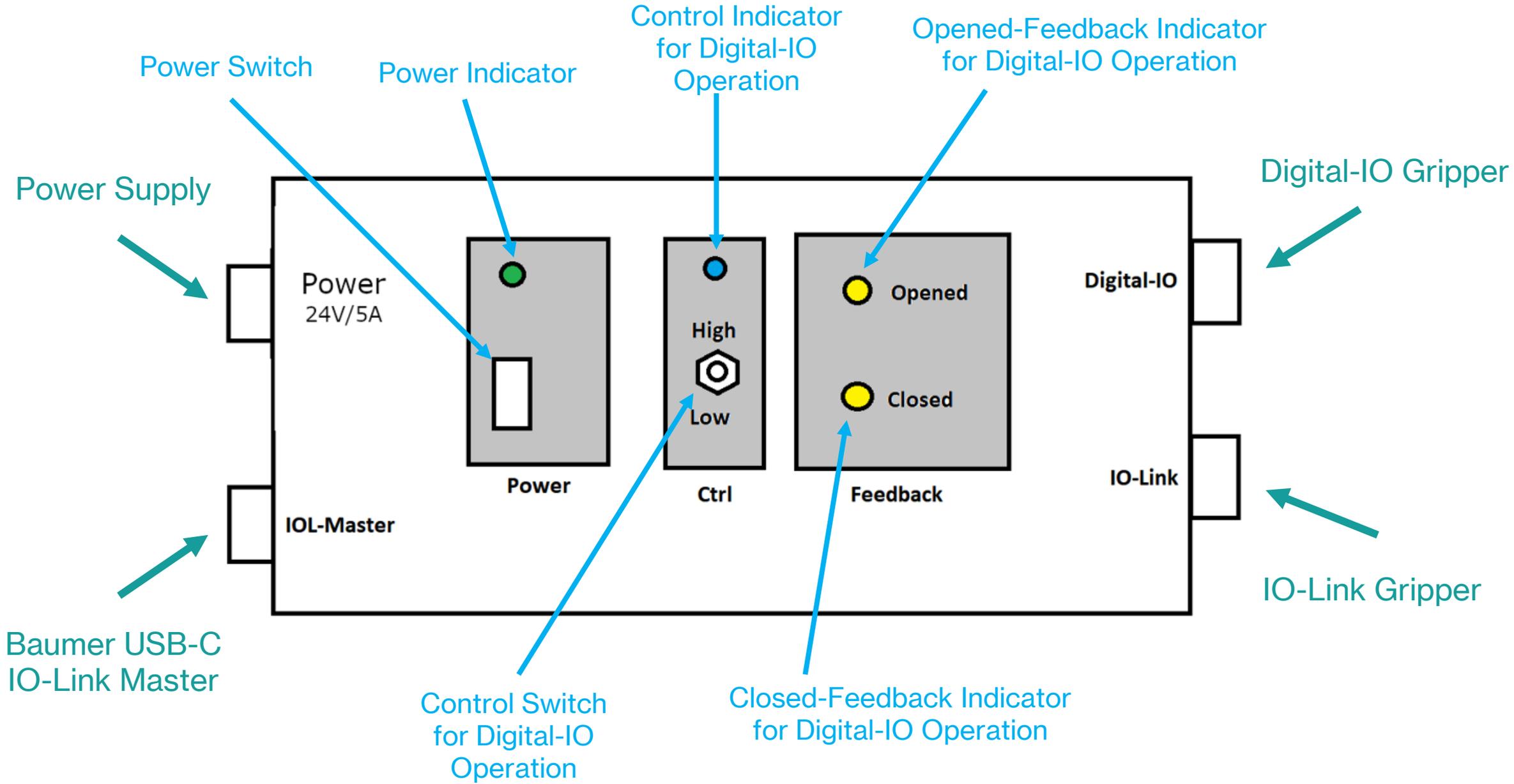


# **MotiAct MX Control-Box**

**OE013118**



# Digital-IO Operation

1. Connect power supply
2. Connect gripper
3. Set power switch to ON
4. Open/Close gripper using control switch

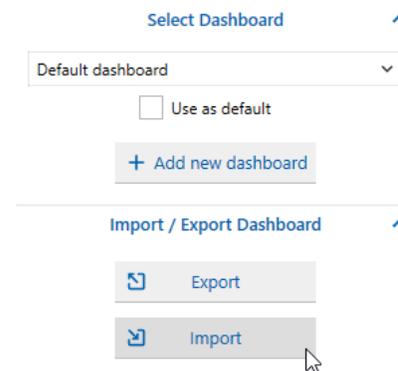
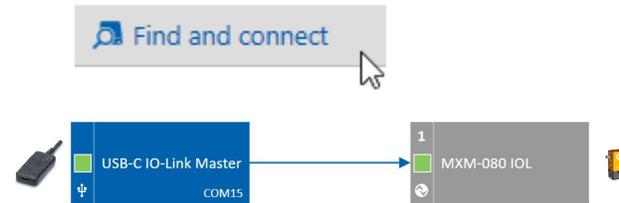
Feedback can be observed using the feedback indicators

# IO-Link Operation

1. Connect power supply
2. Connect Baumer USB IO-Link Master
3. Connect Gripper
4. Set power switch to ON
5. Open Baumer Sensor Suite software on your PC

# IO-Link Operation

1. Press Find and connect button
2. Master and gripper should be found
3. Click on the gripper
4. Import the provided dashboard



The gripper can now be controlled by toggling the control bits or changing parameters